Curriculum Vitae: Professor Dr. Ebrahim A. Mattar

CONTACT INFORMATION Professor of Robotics and Cybernetics

College of Engineering Fax: + 973 1768 0924

University of Bahrain e-mail: ebmattar@uob.edu.bh - IET e-mail:: ebrahim.mattar@ietvolunteer.org

 $Voice: +973\ 1787\ 6606\ -\ 17876286$

P.O. Box 32038 WWW: https://www.dr-e-mattar-uob.com/ Kingdom of Bahrain

Currently: Chair of the University of bahrain Central Academic Promotion Committee. College of Engineering Postgraduate committee Head. Member of the University Postgraduate

Studies Council.

Research Interests

Research Interests: Robotics, Artificial Intelligence, Cybernetics, Working on building AI-Based models for Imaginary analysis, Electroencephalography (EEG) Decoding; to Enhance Robotics Cognition. This is used for the Robotics in the Healthcare/Medicine applications and sectors.

1999-2000

University of Virginia:

Charlottesville, USA.

The Gulf Executive Development Program. Nine Months Program, May-1999 to February-2000 Darden School of Business - University of Virginia. Scholarship was financed by University of Bahrain. January-2000.

EDUCATION

1989-1995

University of Reading:

Reading, Berkshire, United Kingdom.

Doctoral Degree in Cybernetics, January-1995 Dissertation Topic: "Task Space Robot Hand Manipulation and Optimal Distribution of Fingertip Force Functions". Supervision: Thesis was written under the supervision of Professor K. Warwick, University of Reading, UK.

January-1995.

1988-1989

University of Southampton:

Southampton, United Kingdom.

M.Sc. program, in Electronics, September-1989. Dissertation Topic: "CMOS Transistor Measurement in Semiconductors Fabrication", University of Southampton, UK.

September-1989.

1980-1986

University of Bahrain:

Isa Town, Kingdom of Bahrain.

B.Sc. in Electrical Engineering, University of Bahrain, Bahrain.

August-1986.

PRIME HONORS AND

Awards

1995: Late Amir H.H. Shaikh Isa Bin Salman Al Khalifa (Eid Ailm Award), for Ph.D. Award, 1995. 2018: IEEE-EPSCICON-2018, Appreciation Award, EPSCICON 2018, Thrissur, 5-9 January, India, 2018.

ACADEMIC EXPERIENCE University of Bahrain, College of Engineering, Kingdom of Bahrain.

Academic Staff Member

Since I joined University of Bahrain during 1996, I have been involved for a number of duties. Duties included academic responsibilities, lecturing, university duties, community duties, research, research and involvement in postgraduate teaching. This included the current Ph.D. research, Masters level course-works and research/consulting projects. Major teaching duties: Duties included shared administrative responsibilities with faculty instructor, fielding of all student inquiries, and oversight of graduate student teaching assistants and graders. Duties at various times have included office hours and leading weekly laboratories and engineering design exercises.

University of Reading, Department of Cybernetics, UK.

Instructor during Ph.D. Study

1989-1995

1996-present

During the Ph.D. thesis work at University of Reading, I have been involved for teaching in laboratories, tutorials, and homework assignments. Courses included:

Electronics, Control, and Robotics, Spring 1989-1995.

University of Bahrain, College of Engineering, Kingdom of Bahrain.

Part Time Teaching Assistance

1986-1988

After B.Sc. graduation, i.e. during 1988, I was involved in teaching in part time basis few courses related to principles of Electrical Engineering. Courses included:

• Electronics, Electrical Circuits, and Control, Spring 1986-1988.

Research Links

Researchgate Online: https://www.researchgate.net/profile/Ebrahim_Mattar, (19.53).

Scopus Record: https://www.scopus.com/authid/detail.uri?authorId=37661782600

Orcid: https://orcid.org/0000-0002-1536-1074

Google Citations: https://scholar.google.com/citations?user=Zj3wnrgAAAAJ&hl=en, (h-index=15, i10-index=16).

Computational Skills Computational Packages: Expert in using computational packages like Matlab, Mathematica, Labview,; NaG (Library). Languages: C++, Opency, extensive use of C++ and Fortran libraries (as for ISML libraries), Object Oriented Programming skills, Applications: LaTex, and presentation software. Algorithms: Experience programming for a number of AI related Algorithms. Operating Systems: Skills for both Linux and Windows.

Dates/Granting

OTHER CERTIFICATIONS, 2019, Certificate for "Microsoft Azure Machine Learning Workshop".

2014, Certificate for "Reflective Academic Practice Portfolio (RAPP), University of Bahrain. 2013, Certificate for "University Academic Integrity and Plagiarism", University of Bahrain.

2012, Certificate for "First Aids Workshop, The College of Health Sciences - University of Bahrain.

2012, Certificate for "Good Apprenticeship Policy and Practice, UK Study Tour", British Council-London, 30th Jan-

uary - 2nd February 2012. Grant was through Ministry of Education - Bahrain.

2012, Certificate for "Middle East Tech Education", Sudan 9-12 April 2012 via ICESCO. Grant was through Ministry of Education - Bahrain.

2011, Certificate for "Building Effective Employer Engagement in Vocational Education", Tunisia - British Council-

December 2011. Grant was through Ministry of Education - Bahrain. 2008, National Instruments LABVIEW Certificate of Programming Level-1, Lebanon.

2008, National Instruments LABVIEW Certificate of Advanced LABVIEW Programming, Lebanon.

2002, British Council Certificate, Education and Industry Working Together, University of Birmingham, UK.

2001, Certificate of Internet Web Design, the University of Iowa-University of Bahrain.

1997, Certificate of Academic Teaching Development, University of Bahrain, Bahrain.

1989, Certificate of "English for Academic Practices", University of Southampton, UK.

PROFESSION/ADMIN Positions

During my academic career, I have been involved in a number of administration duties, as listed below:

newline 1996, Appointed as Assistant Professor at College of Engineering, University of Bahrain.

1998, Director of Continuing Eng. Education Dept., University of Bahrain, 1998-2002.

2004, Promoted to rank of Associate Professor at College of Engineering, University of Bahrain.

2004, Chairing Electrical and Electronics Engineering Dept., University of Bahrain, 2004-2009.

2011, While at UOB, I was also seconded as the DG - Director General - of Bahrain Training Institute, (BTI).

2011, Chairing of Electrical and Electronics Engineering Dept., University of Bahrain, 2011-2013.

2014, Member of Bahrain National Higher Education Skills-Innovation Steering Committee, 2014-2016. 2019, Member of Muharraq Governorate Council Consultation Board, as in HH Prime Minister Decree, 2019-2023.

2021, Promoted to the rank of Professor at College of Engineering, University of Bahrain.

University Services

Contributed to University of Bahrain, and Bahrain Training Institute (BTI during my seconded position as GD), with quite large number of administration duties, committees, and assigned duties.

Community Services

Contributed to the community with large number of professional activities, duties, and professional committees works.

Profession APPRECIATIONS

Received a number of appreciations. These are few selections.

1999, University of Bahrain, "UOB Deanship" Best Funded Research Award.

2001, University of Bahrain, "College of Engineering" Best Funded Research Award.

2001, Kuwait University, GGC Deanships for Continuing Education, Award.

2001, University of Bahrain, Best Engineering Graduating Project Award.

2007, Bahrain Society of Engineers, Society Contributions.

2012, General Directorate of Traffic Dept. (Ministry of Interior) Award.

2012, Ministry of Education Appreciation, MOE Minister, (Ministry of Education).

- 2014, IEEE-EPSCICON-2014, Appreciation Award, EPSCICON 2014, Thrissur, 8-10 January, India.
- 2014, Appreciation Award from the Bahrain Royal Filed Force Engineers.
- 2014, ABET Achievement and Accreditation Award, University of Bahrain.
- 2015, Bahrain Parliament Appreciation.
- 2015, Appreciation from VEX Robotics Competition.
- 2015, Recognition from IEEE ESEC-2015 Steering committee for the Engineering Ethics Competition.
- 2015, Bahrain Higher Education Appreciation, 2015.
- 2015, University of Bahrain President Appreciation.
- 2017, University of Bahrain Award. UOB winning Hackathon.
- 2018, IEEE-EPSCICON-2018, Appreciation Award, EPSCICON 2018, Thrissur, 5-9 January, India.
- 2018, Appreciation for active volunteering from the IET- The Institution of Engineering and Technology, UK.
- 2019, Appreciation from Canadian University Dubai, for chairing the 5th IET GCC Robotics Challenge.

IET PROFESSIONAL MEMBERSHIPS AND AFFILIATION

IET: Member of Institute of Engineering and Technology (IET,UK), from 1991-Till now. In addition, a member in IET professional networks (TN): like (Control-Automation), (Robotics and Mechatronics), (Image Processing and Pattern Recognition). Bahrain local network chair, and IET Europe Middle East Africa Regional Board Member for two sessions, (2009-2012),(2016-2019), MIET. I am an active volunteering member with the IET, where I am responsible in organizing several forums, symposiums, events, and local events.

IEE PROFESSIONAL MEMBERSHIPS AND AFFILIATION

IEEE Senior Member of Institution of Electrical and Electronics Engineering, (1991- until now). In addition, member in (Robotics and Automation Society, System-Man Cybernetics Society, Fuzzy Systems Society, Artificial Neural Network Society, Mechatronics Society, Control System Society, and Control Education Society), MIEEE. Member of Institute of Engineering and Technology (IET, UK), from 1991-till now.

IFAC AND BSE PROFESSIONAL MEMBERSHIPS AND AFFILIATION

Affiliate Member of the European IFAC (1995-until now), AIFAC. Member of Bahrain Society of Engineers (BSE), (1995-until now), MBSE. Member of International Neural Network Society (INNS), (1995- until now). Previous Memberships: Member of American Society for Mechanical Engineers (ASME), Automatic Control Division (1995-1998). Board Member of Bahrain Academic Society, Bahrain (2005-2008). Board Member of Technology Transfer Society, Bahrain (2006-2008).

ACADEMIC TEACHING ACTIVITIES

I have been involved in academic lecturing with substantial materials.

(a.) Before Ph.D., during 1989-1994, during Ph.D. thesis works, I was assisting teaching related for undergraduate students laboratories at (University of Reading, UK)). This involved electronics, control, robotics, experiments, and tutorials

University of Bahrain Academic Lecturing:

Courses for B.Sc. Studies:

EENG205 Numerical Methods, EENG271 Signals and Systems, EENG381 Control Systems, EENG400 Engineering Ethics, EENG482 Robotics and Automation, EENG483 Discrete-Time Systems, EENG485 Nonlinear Systems, EENG486 Intelligent Systems.

POSTGRADUATE PROGRAM:

Courses for M.Sc. Studies:

EEG580 Linear and Nonlinear Dynamics, EEG581 Intelligent Systems, EEG582 Digital Control Systems, EEG583 Optimal Control Systems, EEG586 Machine Vision, EEG570 Probability and Stochastic Processes, EEM600 Principles of Artificial Intelligence, AIE605 Special Topics in Artificial Intelligence. CSCI650 Computer Algorithm Concepts, CSCI635 Probability and Stochastic Processes, CSCI720 Discrete-Time Control Systems, CSCI741 Computer Architectures.

Doctor of Philosophy in Engineering:

Courses for Ph.D. Studies:

 $ENGG701\ Advanced\ Numerical\ Methods,\ ENGG702\ Finite\ Element\ Methods,\ ENGG703\ Optimization\ Techniques,\ ENGG791\ Research\ Methodologies.$

More details and contents are found over the website link:

https://www.dr-e-mattar-uob.com/

(e.) THESIS SUPERVISION - M.Sc., and Ph.D. thesis titles:

Fuzzy Modelling and Analysis for Nonlinear Dynamic Systems Multivariable Neuro-fuzzy Model Predictive Systems Systems Optimization via Fuzzy Logic System Neuro-Fuzzy Architectures Based Energy Optimization Predication with an Evolving ANN Structures - Evolutionary Programming Deep Learning based Robotic Recognition System for Crowd Management Adaptive Fuzzy-Neural-Approach Hinf Sliding Mode Control of Induction Generator- Motor

Electroencephalography Emotional Enhancements of Detection, and Classification Integrating GIS and Decision Based Systems in Energy Management Systems Deep Learning Topology in Islanding Detection for Distributed Generation Sags-Swells.

For details, visit the link: https://www.dr-e-mattar-uob.com/

SUPERVISION -UNDERGRADUATE PROJECTS

I have been involved in supervising a number of graduating projects. Some of these projects have received the best project awards by UOB. Below are few samples of these projects:

(a.) Neural Network for Nonlinear Control Systems. (b.) LMI-Based Fuzzy Gain-Scheduling For a Nonlinear Benchmark Control Problem. (c.) Fuzzy Intelligent House, (d.) Gain Scheduled Hinf Control of a Nonlinear System via Linear Matrix Inequalities. (e.) Nonlinear Systems Genetics Identification. (f.) Iris and Face Recognition System, (g.) Robust Optimal Neural Network Control of Robots. (h.) Fuzzy Control of Home Built Robotics Arm system, (i.) RBF for Visual Hand Control. (j.) Visual Servoing using Artificial Neural Networks. (k.) Visual Servoing ANN Based for Learning Jacobian Nonlinearity Approximation. (l.) High Speed Vehicle Speed Detection, m. Stereo-Vision Based Mobile Robot Navigation. (n.) EEG Brainwaves Based Robotics Grasping. (o.) SVM Based Electroencephalography (EEG) Analysis for Eye Movement. (p.) Electroencephalography (EEG) Analysis for Hand Movement: Events Features Detection, Classification, for Cybernetics and Robotics Applications. (q.) Eye-Electroencephalography Analysis and Understanding, Towards Robotics Learning. (r.) EEG Based Robotics System with Common Spatial Patterns and Adaptive Boosting Algorithms. Gradient Boosting Machines Learning for Discrete Wavelet Classification of EEG Patterns. (t.) LDA - Power Spectral Density Based EEG Classification Applied for Facial Recognition System.

Grants and Funded Project

During my academic career, I have worked on a number of granted research projects. These are funded projects by different funding bodies including UoB. This is indicated in the below list:

- (a.) UN-DEP. Energy Saving in Bahrain: Technical Report submitted to the University of Bahrain and UN-DEP in Bahrain. Funding Body: United Nation -DEP, Bahrain Qamber I. and Mattar E., 1998.
- (b.) Energy Saving and Intelligent House Automation: Study Report submitted to the University of Bahrain, Deanship for Scientific Research. Funding Body: Deanship for Scientific Research, University of Bahrain Mattar E., 1998.
- (c.) Bahrain Social-Cultural and Educational-Training Dimensions in Flattering Job Creation Educational, Cultural and Social. Prospects with Restructuring Policies, Technical Report of DARDEN School of Business Visit. Darden Business School, University of Virginia, USA. Mattar E., Bosera A. and Al-Hashimi A. and Amin K., 1999.
- (d.) Extruded Insulation and Their Accessories for Rated Voltages. Ministry of Industry. ABOVE 150 kV (Um = 170 kV) up to 500 kV (Um = 550 kV). TEST METHODS AND REQUIREMENTS.
- (e.) Gulf Executive Program in Management in Darden. Technical Report of DARDEN School of Business visit submitted to University of Bahrain Funding Body: University of Bahrain. Mattar E., 2000.
- (f.) Neural Network Face Recognition Via (PCA) Principle Components Analysis. Research project submitted to Deanship of Scientific Research. Sponsorship: Deanship for Scientific Research, University of Bahrain. Mattar E. and Al-Ruwihi K.,2000.
- (g.) Engineering Job Creation in Bahrain Over the Coming Ten Years. Research study submitted to the Deanship of Scientific Research, Funding Body: Deanship for Scientific Research, University of Bahrain. Mattar E. and Al-Ruwihi K.,2000.
- (h.) Neural Network Financial Stock Market Predication. Technical research submitted to Deanship of Scientific Research. Funding Body: Deanship for Scientific Research, University of Bahrain. Mattar E. and Al-Mutawia S. (Cairo University, Egypt). 1998.
- (i.) Designing a 3-DOF Robotics Arm System for UOB. Research work submitted to UOB. Funding Body: Sponsored by UOB and External Company in Bahrain, Mattar E., 2000.
- (j.) Designing a Mobile Robot Navigation System. Research work submitted to UOB. Mattar E., 2004.
- (k.) Modeling of Materials Internal Physical Parameters, Project Report submitted to Bahrain Welding Wire Products Funding Body: Sponsored by Bahrain Welding Wire Products, Bahrain, Mattar E. 2007.
- (l.) Aluminum Rod Bar Micro-Ohm Resistance Measurements. Project Report for a funded research work to measure Aluminum Rod Bar Micro-Ohm Resistance. Mattar E. 2008.

- (m.) Intelligent Mobile Robotics System: Intelligent Interaction Capabilities with an Active Stereo Vision: Path Planning Navigation in Unstructured Hazardous Environments, Al Mutib K., Mattar E. Ramdane H., Al Sulaiman M., Abdsemed F., Mathkour H. and Arafah M., 2010. Funding Body: Sponsored by King A. Aziz City for Science and Technology, Kingdom of Saudi Arabia.
- (n.) Fingerprint Patten Recognition System, Sponsored by King A. Aziz City For Science and Technology, Kingdom of Saudi Arabia. Al Mutib K., Mattar E. Ramdane H., Al Sulaiman M., Abdsemed F., Mathkour H. and Arafah M., 2008. Funding Body: Sponsored by King A. Aziz City for Science and Technology, Kingdom of Saudi Arabia.
- (o.) High Speed Visual Vehicle Detection on Bahrain Highways. Project Report submitted to Deanship of Scientific Research. Funding Body: Deanship for Scientific Research, University of Bahrain. Mattar E., 2010.

INVITED TALKS -SELECTED SAMPLES

I have been invited for a number of Technical Content Talks. Some of which were locally presented and some were presented out of Bahrain. Below are few selections.

Local Invited Talks:

(a.) Intelligent Stock Predication via Artificial Neural Networks, Business Administration College, University of Bahrain, 1996. (b.) Intelligent Controllers, University of Bahrain, 1996. (c.) Intelligent Robotics Systems, Global Institute 6th Annual Seminar, Global Institute, 1998. (d.) Genetic Algorithms for Optimization and Control Applications, University of Bahrain, 1998. (e.) Artificial Neural Networks Applications, Bahrain Society of Engineers, 1997. (f.) Intelligent Robotics Systems, IEE-Bahrain Section, Bahrain, 1999, g. Welding Robotics Control System, Gulf-Matech Conference, (Keynote Lecture), 2002. (h.) LMI Based Robust Fuzzy Stabilization of a Nonlinear Dynamic System, University of Bahrain, 2003. (i.) Mathematica for Engineering Applications, University of Bahrain, 2005. (j.) Visual Servoing Nonlinearity Approximation Via an Intelligent Approach, University of Bahrain, 2007. (k.) IET Professional Society, BTI Bahrain, 2008. (l.) Iris Recognition System, Sheikh KHALIFA Institute of Technology, 2009. (m.) Digital Revolution: where we are Heading, Talk to Sri Lankan Engineering Society, 2013. (n.) Medical Robots for Disabled, Talk to Bahrain Mobility International, 2014. (o.) Ministry of Education 2016 Innovation Day (Future Scientists Training Program), 2016.

International Invited Talks:

(a.) Fuzzy Decision Based Mobile Mapping, King Saud University, KSA, 2013. (b.) Occupancy Grids and Stereo Vision SLAM Navigation: Neuro Occupancy Mapping, (Keynote Lecture), Presented at EPSCICON-2014, India, 2014. (c.) EEG Brainwaves for Robotics and Prosthesis Grasping and Motorization, (Keynote Lecture) Presented at ICKEA 2015, UAE, 2015. (d.) Michael Faraday IET International Summit-2015, (MFIIS 2015), an IET International Conference Focused Area Power-Control-Automation, September 12-13, 2015, Kolkata, India. Supported By: IET Control and Automation (UK), IET Power Electronics, Machines and Drives (UK), Technical Sponsor: Dept. of Applied Physics, University of Calcutta, India, 2015. (e.) EEG Complex Grasping Patterns Recognition for BMI Robotic and Prosthesis Motion Control, Keynote Lecture, MFIIS-2015, India, 2015. (f.) Electroencephalography Based Event Features Extraction for Robotics Advanced Learning, Mauritius, 2017. (g.) Workshop for Two Days about (Machine Learning Based Brainwaves Electroencephalography EEG Decoding and Understanding), during the FOURTH International -Conference- EPSCICON 2018 - IEEE, 3-4 January 2018, at Vidya Academy of Science and Technology. India 2018. (h.) Invited for Talk at the (2nd Annual Techno and Science) in the GCC 2018, 22-24 February 2018, (Al Hifof), KSA. (i.) Artificial Intelligence and Smart IoT Based Energy Conservation in Buildings: A Learning Paradigm Approach, UAE-2020.

Workshops, Summer Schools, Short Courses Organizations: During my academic career, I have been involved in organization of a number of technical /Workshops/Short Courses/ Summer School events. Below are few selections of these events:

(a.) Basic Web Technology Skills for Courseware Development (October 14-18, 2001) in cooperation with the UNESCO office. (b.) Power System Planning and Control", Short Course, University of Bahrain, 1998. (c.) Programmable Logic Controllers PLCs, University of Bahrain, Two weeks intensive course, 2000. (d.) Industrial Process Control, University of Bahrain, a four days Short-Course, 2000. (e.) Internet Technology for Non Expert staff, 2000. (f.) Responsible for organizing a Training Workshop (14-18 October 2001) for the UISCO Office on using internet for educational purposes, entitled". Basic Web Technology Skills for Courseware Development ", 2001. (g.) MATLAB FOR ENGINEERS: A fully developed programming in Matlab Sessions for Students, 2003. (h.) Plant Automation and Control, Bahrain, three days intensive short course, 2005. (i.) Programmable Logic Controllers PLCs, Bahrain, Three days intensive course, 2005. (j.) Plant Automation and Control, in KSA, three days intensive short course, Kingdom of Saudi Arabia, 2007. (k.) Process Instrumentation and Control, a one week intensive workshop for ASRY, 2007. (l.) Plants Programmable Logic Controllers and Automation, 24th - 26th, November, Kingdom of Bahrain, 2009. (m.) Electrical Fundamentals, Bahrain Defense Force Trainee, 2010. (n.) Scientific Report Writing, for RE-

SEARCH METHODOLOGY AND ENTREPRENEURSHIP, 4-8 October 2015. (o.) IEEE 2016-Engineering Ethics Competition. (p.) IET GCC Annual Robotics Challenge. (q.) Annual IET Smart Cities Symposium.

Conferences. Program Committee. PROJECT PROPOSALS

REVIEWING: JOURNALS, Reviewing of scientific contributions was essential during my career. I have been involved in reviewing of manuscripts for a number of journals/conferences. Below are few selected samples:

> (a.) International Journal of Advanced Robotic Systems. (b.) Robotik Journals, Germany (Editorial Advisory Board). (c.) International Journal of Intelligent and Robotic Systems, Springer. (d.) International Journal of Nonlinear Control, Springer. (e.) International Journal of Mechatronics, IFAC. (f.) Journal of Applied Informatics. (g.) International Journal of Robotics and Autonomous Systems, Springer. (h.) International Journal of Intelligent and Robotic Systems. (i.) Journal of Zhejiang University-SCIENCE. (j.) 3rd IEEE-GCC 2006 International Conference. (k.) IEEE International Conference on Signal Processing and Communication-2007. (l.) International Association of Science and Technology for Development, International conference on Optical Communications-2006. (m.) International Association of Science and Technology for Development. (n.) International Journal of Advanced Robotic Systems, Austria. (o.) International Journal of Sensors and Actuators: A. Physical, 2017. (p.) Journal of ScholarOne Advanced Robotics, 2017. (q.) IFAC, 12th IFAC Conference on Control Applications in Marine Systems, (r.) Robotics, and Vehicles 1st IFAC Workshop on Robot Control.

EDITORIAL BOARDS AND During my academic career, I have been involved in specific editorials of manuscripts for a number of journals/conferences. TECHNICAL COMMITTEES These are few samples.

> (a.) Technical Committee on Soft Computing, (2001-2004). (b.) IASTED Technical Committee of the International Conference on Intelligent Systems and Control, (2003). c. International Journal of Advanced Robotic Systems — InTech, (2010). (d.) IET SEISCON International Advisory Board, (2010). (e.) International Advisory Committee and Technical Reviewer of the ICTES-07,(2007). (f.) IET International Conference on Intelligent Systems,(2008). (g.) IET SESCON-2011, YPS Chennai, (2011). (h.) Consumer Electronics Times Journal, (2014). (i.) Research and Educational Society Editorial/Reviewer Board Member. (j.) Journal of Instrumentation, Automation and Systems, (2013). (k.) Journal of Frontiers Journal, (2014). (l.) Journal of Advances in Robotics and Automation, (2014). m. Reviewer and Technical Committee of Int. Conference on Mechatronics and Intelligent Manufacturing (ICMIM 2014), 2014. (n.) International Journal of modern Computer Science and Applications.

TECHNICAL SESSIONS CHAIRING

I have been involved in chairing technical sessions for a number of technical meetings/events/conferences.

(a.) Gulf Cooperation Council (GCC), Technical and Education Colleges Meeting, University of Bahrain, Bahrain meeting during 1998. (b.) Gulf Cooperation Council (GCC), Continuing Education and Community Services Colleges in GCC, University of Kuwait, Kuwait-2001. (c.) MDTCE-2001 Board of Members Meeting, Bahrain, 9th of April 2001. (d.) University and Industry Corporations in Information Technology Symposium), 25th May 2003. (e.) IET-International Conference on Intelligent Systems (ICIS-2008), 1-3 December, Bahrain 2008. (f.) MEST 2009 International Conference, Bahrain, 2009. (g.) IEEE-EPSCICON 2010, International Conference on Power, Signals, Control and Computation, India, January 2010. (h.) 14th UK-Sim AMSS (International Conference Modeling and Simulation), UKSim-2012, University of Cambridge, 28-30 March 2012. (i.) 14th UK-Sim AMSS (International Conference Modeling and Simulation), UKSim-2012, University of Cambridge-March 2012. (j.) Arabian for Education, Culture and Sciences Organization, ALECSO), Sudan, 9th of April 2012. (k.) 15th UK-Sim (International Conference Modeling and Simulation), UKSim-2013, at UKSim2013, University of Cambridge, April 2013. (l.) 5th International Conference Intelligent Systems, Modeling and Simulation, Malaysia, January 2014. (m.) Chairing a Technical Session-2016 17th WERNC, 2016. (n.) Chairing a Technical Session at, 2017 9th IEEE-GCC Conference and Exhibition (GCCCE), 2017. (o.) Chairing of a Technical Session (Smart Health Care) during the 1st IET Smart Cities Symposium, (SCS-2018), University of Bahrain, 2018. (p.) Chairing of a Technical Session (Machine Learning and Robotics) for IEEE-3ICT International Conference, (3ICT-2018), University of Bahrain, 2018. (q.) Chairing a Technical Session (Robotics Manipulators), at the IEEE ROBIO-RAS 2018, December 2018, Kuala Lumpur Malaysia. (r.) Chairing of a Technical Session (Smart Health Care), during the 2nd IET Smart Cities Symposium, (SCS-2019), University of Bahrain, 2019.

University Academic I have been involved in university academic duties matters. Contributed Matters Below are few selections: (FEW SELECTIONS)

(a.) Member of Committee for Electronics Colloquium Development, 1997-1998. (b.) Head of ABET Department

Accreditation Committee. (c.) Member of Department for research on Robotics, DSP Applications, (2009-Now). (d.) Member of Academic Committee, (2010-Now). (e.) Head of College of Engineering Information Committee, (1999-2003). (f.) Member of College of Engineering Task Force Strategic Committee, (1999-2002). (g.) Head of Organizing Committee for International Conference on (Millennium Dawn in Training and Continuing Education), (1999-2001). h.) Head of College of Engineering Administration Staff Grievance Committee, (2005-2005). (i.) Member of College of Engineering Committee for (Summer Courses Regulations), (2005-2005). (j.) Head of College of Engineering Administration Staff Grievance Committee, (2006-2006). (k.) Member of University Strategy Committee for Planning the Community Service College, (1999-2001). (l.) Member of University Committee for Observation and Setting Standards for UOB Graduates. (m.) Member of (Industry-University Collaboration in Information Technology Forum organized by University of Bahrain, 2002-2003). (n.) Member of University of Bahrain Committee in providing a program for "Training and Employment of Bahrain Nationals". (o.) Member of Administration Staff Grievance Council, (2001-2003). (p.) Member of University Committee for IT and IT related Equipment, (2000-2003). (q.) Member of Research Deanship Information Technology Advisory Committee, (2000-2003). (m.) Head of UOB ACs and Power Cables Tender Selection Committee, (2007-2008). (n.) Member of UOB Scientific Research Funding Committee (A Part from the UOB Strategy Committee), (2010-2012). (o.) Member of Colloquium Development for the Ministry of Education, (1996-1999). (p.) Member in "Committee of Deans and Directors of CT's in GCC, (1998-2003). (q.) Member of GCC Deans of Community Services and Continuing Education Colleges. (r.) Member of GCC special task force committee for setting Technical Education Strategy in the GCC. (s.) Head of Quality Assurance Accreditation Committee, (2010-until now), responsible for preparing the quality reports. (t.) Head of Quality Assurance Accreditation Committee, (2010-until now), responsible for preparing the ABET engineering reports for three times. (u.) Head of Quality Assurance Accreditation Committee, (2017-until now), responsible for preparing the National Qualification Reports. (v.) Head of academic recruitment committees for a number of times.

PROGRAMS AND COURSESPrepared technical contents for the following Undergraduate Courses:

CURRICULUM DEVELOPMENT (i.) Automatic Control. (ii.) Electrical Measurement Systems, (iii.) Nonlinear Control System. iv. Robotics Systems. (v.) Intelligent Control Techniques.

In addition, I have contributed in preparing technical contents for a number of Postgraduate Courses. This includes: (i.) Linear and Nonlinear Dynamic Systems. ii. Discrete Time Control. (iii.) Optimal Control Theory. (iv.) Robust Multivariable Control System, (v.) Intelligent Control. (vi.) Principles of Artificial Intelligence. (vii.) Special Topics in Artificial Intelligence.

TECHNICAL CONFERENCES, EVENTS AND ORGANIZATIONAL COMMITTEES

(a.) Organizing Head of the 5th Annual GCC Technical Collages Meeting, 2001. (b.) Organizing Head for the International Conference on (Millennium Dawn in Training and Continuing Education), 2001. (c.) Engineering Software Workshop-1, 2006, Mathematica for Engineering Applications. d. Engineering Software Workshop-2, 2007, MatLab for Engineering Applications. (e.) Member of the Organization Committee of the 1st Technology Transfer Conference, Bahrain, 2004. (f.) Member of the Organization Committee of the 2nd Technology Transfer Conference, Bahrain, 2006. (q.) Member of IEEE Control Systems Society, Technical Committee on Control Education. (h.) Technical Chair of IET ICIS-2008 International Conference on (Intelligent Systems), December 2008. (i.) Organizing committee of IET Colloquium and Forum (Wireless Communications Forum), Bahrain, 2008. (j.) Organizing committee of IET Colloquium and Forum (New Directions in Automatic Control: Theories and Applications), 2010. (k.) Gulf Research Conference Committee Members, 2010. l. Board Member of the IET Executive Control and Automation TPN Network, 2010. (m.) Head of organizing committee of IET Symposium (Robotics and Artificial Intelligence Applications in GCC), 2011. (n.) Organizing committee of IET Colloquium and Forum (New Directions in Automatic Control: Theories and Applications), 2012. (o.) Organizing committee of IET Colloquium and Forum, "Control and Automation Education: Exploring Automatic Control Education in Academia and Industry Associated with Control and Automation Show, 2014. (p.) IEEE Steering Committee Member of the GCC Engineering Ethics Competition, 2015, UAE. (q.) IEEE Steering Committee Member of the GCC Engineering Ethics Competition, 2016, Bahrain. (r.) Organizing Committee Member of IET Colloquium and Forum (Engineering Trends in Image Processing, Pattern Recognition Techniques, and Applications), Bahrain, 2016. (s.) Organizing Committee member of the 17th WREN Congress. (t.) Head of the Organizing Committee of 3rd IET/GCC Robotics Challenge, 21 April 2018. (u.) Organizing Committee member of IET/EMEA (Smart Cities Symposium), 22-23 April 2018. (v.) Organizing Committee member of International Conference on Fourth Industrial Revolution 19-21 February, Bahrain 2019. (w.) Organizing Committee member of IET-EMEA (2nd Smart Cities Symposium), 24-26 March 2019. (x.) 2021 6th International Conference on Robotics and Machine Vision (ICRMV 2021), China, Guangzhou.

IET FORUMS, VOLUNTEERING, IET ANNUAL SMART CITIES AND THE IET GCC ROBOTICS CHALLENGES: I am a member with the IEE (now the IET) since 1990. I am an active member of the (IET) since 1995. I got more involved with IET volunteering during 2006. Since that time we have organized the first IET local forum in Bahrain during 2008. After that, during the next 10 years, we were able to organize annual events as local forums. Forums themes included (Control, Automation, AI, Image Processing, Renewable Energies, Robotics, IoT, ...).

By 2017, we stated to think differently and expand the thoughts of technical meetings and event. Smart Cities

and the IET GCC Robotics Challenges, are two main IET Annual events within the EMEA region, that have been proposed to the IET, to serve the young professionals, the academic communities, and industrial affiliates. Since that time, that have been started to run, theme of the two annual events do reflect on the advances and the development related to (Smart Solutions) and (Robotics).

PUBLICATION LIST: (i): Refereed Journals Articles: JOURNALS

J-01: Al-Sammak A. and Al-Gallaf E., "Adjustable Frequency Dependent Switch, "Journal of Modeling, Simulation and Control, Part A: , AMSE Press, Vol. 38, No. 2, pp.59-64, 1993.

J-02: Al-Gallaf E., Allen A., and Warwick K., "A Survey of Multi-fingered Robot Hands: Issues and Grasping Achievements," International Journal of Mechatronics, vol. 3, No.4, DOI: 10.1016/0957-4158(93)90018-W, IFAC-Journal, International Federation of Automatic Control, pp. 465-479, Oxford, UK, 1993.

J-03: Al-Gallaf E., Allen A., and Warwick K., "Dexterous Hands: Issues Relating to a Four Fingered Articulated Hand," International Journal of Mechatronics, Vol.3, No. 3, DOI: 10.1016/0957-4158(93)90007-O, IFAC- Journal, International Federation of Automatic Control, pp. 329-342, Oxford, UK, 1993.

J-04: Al-Gallaf and Warwick K., "Force Distribution in Manipulation by a Robot Hand with Equality and Non-linear Inequality Constraints, "The International Journal of Mechatrontics, Vol. 5, No.5, IFAC- Journal, International Federation of Automatic Control, pp. 561-583, Oxford, UK, 1995.

J-05: Al-Gallaf E., "Manipulation At Ill-Conditioned Configurations By A Robot Hand (Employment of Local and Global Dexterities), "The International Journal of Mechatrontics, vol. 7, no.5, IFAC- Journal, International Federation of Automatic Control, pp. 479-503, Oxford, UK, 1997.

J-06: I. Qamber. and E. Al-Gallaf, "Electric Load Forecasting Model for the State of Bahrain Network," International Journal of Electric Power Components and Systems, Vol. 29, pp. 259-276, USA, 2001.

J-07: Al-Gallaf E., "Artificial Neural Network Based Nonlinear Model Predictive Control Strategy," Journal of Information and Technology, vol. 1, no.2, pp. 173-179, 2002.

J-08: Al-Gallaf E., "Neural Networks Based Inverse Kinematics for Multi-finger Hand Control", International Journal of Robotics and Automation, Vol. 18, No. 11, PART 1, pp. 1-9, Netherlands, 2003.

J-09: Al-Gallaf E., "Neuro-Fuzzy Inverse Jacobian Mapping For Multi-Finger Robot Hand Control, "International Journal of Intelligent and Robotic Systems, Springer Netherlands, 0921-0296 (Print) 1573-0409 (Online), vol. 39, no., pp. 17-42 1, January, Netherlands, 2004.

J-10: Al-Gallaf E., "Neural Networks for Multi-Finger Robot Hand Control," International Journal of King A. Aziz University for Engineering Sciences, JKAU: Engineering Sciences, Vol. 19, No. 1, pp. 19-42 (2008 A.D. /1429 A.H.), KSA, 2008.

J-11: Al-Gallaf E., "Takagi-Sugeno Neuro-Fuzzy Modeling on a Multivariable Nonlinear Antenna System, " Journal of Engineering Research (TJER), Vol. 2, No. 1, pp. 12-24, 2005.

J-12: Al-Gallaf E., "Clustered Based Takagi-Sugeno Neuro-Fuzzy Modeling of a Multi variable Nonlinear Dynamic System," Asian Journal of Control, (ACPA Affiliated Journal), Vol. 7, No. 2, pp. 163-176, June, 2005.

J-13: Al-Gallaf E., "Clustered-Based Takagi-Sugeno Neuro-Fuzzy Modelling Of a Multivariable Nonlinear Dynamic System," A paper accepted for publication in the International Journal of Control and Intelligent Systems, Vol. 34, No. 1, 2006.

J:14: Al-Gallaf E., "Multi-Finger Robot Hand Optimal Task Force Distribution: Neural Inverse Kinematics Approach, "International Journal of Robotics and Autonomous Systems, Elsevier, Vol. 54, DOI: 10.1016/j.robot.2005.09.016, pp. 34-51, 2006.

J-15: Al-Gallaf E., "Neuro-Kinematics Based Dexterous Robotics Hand Force Optimization," Journal of Intelligent and Robotics Systems, Springers Netherlands, Vol. 50, No. 2, pp. 181-206, December, Netherlands, 2007.

- *J-16*: Al-Gallaf E. Al-Meteeb K., and Hani H., "ANN Dexterous Robotics Hand Optimal Control Methodology Grasping and Manipulation Forces Optimization," Publications in AROB Journal ,International Journal of Artificial Life and Robotics, Springer, Vol. 15, No. 4, December, DOI 10.1007/s10015-010-0831-6, Japan, 2010.
- J-17: Mattar E., "Neural Net Robotics Dexterous Hand Force Distribution System", Indian Centre For Advanced Scientific And Technological Research, ICASTOR (Journal of Engineering), Vol.3, No.3, ISSN-0974-407X, September, 2010.
- *J-18*: K. Al-Mutib, M. AlSulaiman, M. Emaduddin, H. Ramdane, and E. Mattar, "D* Lite Based Real-Time Multi-Agent Path Planning in Dynamic Environments", Journal of Engineering Research and Applications (IJERA), ISSN: 2248-9622, pp.1414-1419, Vol. 2, No. 2, April, 2012.
- J-19: E. Mattar, K. Al-Mutib, H. Hamdan, and M. Hamdan, "Bio-inspired Transputer Based-Fuzzy Mobile Robot," J. Suzuki and T. Nakano (Eds.): BIONETICS 2010, LNICST 87, pp. 607-620. Institute for Computer Sciences, Social Informatics and Telecommunications Engineering -2012, Volume 0087 of the Lecture Notes of the Institute for Computer Sciences, Social Informatics and Telecommunications Engineering series, Springer Computer Science, USA, 2012.
- J-20: E. Mattar, and K. Al-Mutib, "Bio-inspired Robotics Hands: A Work in Progress," J. Suzuki and T. Nakano (Eds.): BIONETICS 2010, LNICST 87, pp. 607-620. Institute for Computer Sciences, Social Informatics and Telecommunications Engineering -2012. Volume 0087 of the Lecture Notes of the Institute for Computer Sciences, Social Informatics and Telecommunications Engineering series Springer Computer Science, USA, 2012.
- J-21: E. Mattar, "A Survey of Bio-Inspired Robotics Hands Implementation: New Directions in Dexterous Manipulation", Publication in Robotics and Autonomous Systems, International Journal of Robotics and Autonomous Systems, ISSN: 0921-8890, Elsevier Journals, 2013.
- J-22: E. Mattar, "Principal Components Analysis Based Iris Recognition and Identification System", Journal of Soft Computing and Engineering (IJSCE) ISSN: 2231-2307, Vol.3, No. 2, May, 2013.
- J-23: E. Mattar, "A Practical Neuro-fuzzy Mapping and Control for a 2-DOF Robotic Arm System", International Journal of Computing and Digital Systems, Vol. 2, No. 2, pp. 1-10, May, 2013.
- J-24: K. Al-Mutib, E. Mattar, M. AlSulaiman, H. Ramdane, and M. Emaduddin, "Mobile Robot Floor Navigation using RGB+D and Stereo Cameras", Journal of Soft Computing and Engineering (IJSCE), ISSN: 2231-2307. Vol.3, No.3, June, 2013.
- J-25: Khalid AlMutib, Ebrahim Mattar, H. Ramdane Muhammad Emad AL-Dean", Neural Network Vision-Based Visual Servoing And Navigation for KSU-IMR Mobile Robot Using Epipolar Geometry", International Journal of Soft Computing and Software Engineering [JSCSE], Vol. 3, No. 3, USA, 2013.
- J-26: K. Al-Mutib, E. Mattar, M. AlSulaiman, H. Ramdane, and M. Emaduddin, "Mobile Robot Floor Navigation using RGB+D and Stereo Cameras", Journal of Soft Computing and Engineering (IJSCE), ISSN: 2231-2307. Vol.3, No.3, July, 2013.
- *J-27*: E. Mattar, "A Neurofuzzy Knowledge Based Architecture for Robotic Hand Manipulation Forces Learning", International Journal of Intelligent Mechatronics and Robotics (IJIMR), 109.161.183.154. Vol. 3, No. 2., IGI Global, USA, 2013.
- J-28: E. Mattar and M. Akbaba "A Knowledge Based Neuro-Fuzzy Model and Controller Synthesis of a Highly Nonlinear Dynamics Electrical Machine", International Journal of Soft Computing and Software Engineering [JSCSE], Vol. 3, No. 11, pp. 7-20, 2013, Doi: 10.7321/jscse.v3.n11.2, USA, 2013.
- J-29: E. Mattar, "e-GRASP: Robotic Hand Modeling and Simulation Environment", Journal of Advances in Robotics and Automation, OMICS Group. Journal of Advances in Robotics and Automation, Vol. 2, No.2, 1000109, DOI. http://dx.doi.org/10.4172/2168-9695.1000109, ISSN: 2168-9695, USA, 2013.
- J-30: M. Faisal, K. Al-Mutib, R. Hedjar, H. Mathkour, M. Alsulaiman, and E. Mattar, "Behavior based Mobile for Mobile Robots Navigation and Obstacle Avoidance", International Journal of Computers and Communicati published by NAUN, ISSN: 2074-1294, North Atlantic University Union, January, USA, 2014.
- *J-31*: M. Faisal, K. Al-Mutib, R. Hedjar, H. Mathkour, M. Alsulaiman, and E. Mattar, "Behavior based Mobile for Mobile Robots Navigation and Obstacle Avoidance," International Journal of Computers and Communication, Vol. 8, ISSN: 2074-1294, pp. 33-40, 2014.

- J-32: K. Mutib, M. Emaduddin, M. Alsulaiman, H. Ramdane, and E. Mattar, "Motion Periodicity based Pedestrian Detection and Particle Filter based Pedestrian Tracking using Stereo Vision Camera," International Journal of Intelligent Systems Technologies And Applications, Vol. 50, No. 1/2, 2014, Inderscience, UK, 2014.
- J-33: E. Mattar, "Stereo-Vision Mobile Robotics Navigation through Metric-Topological Learning," Editorial Article, Advances in Robotics and Automation, ISSN:2168-9695, USA. 3:e123. doi: 10.4172/2168-9695.1000e123.
- J-34: Khalid Al-Mutib, Ebrahim Mattar, and Mansour Alsulaiman, "Implementation of Fuzzy Decision Based Mobile Robot Navigation using Stereo Vision, Journal of Procedia Computer Science, ISSN: 1877-0509, Elsevier, 2015.
- J-35: E. Mattar, K. Al Mutib, M. AlSulaiman, H. Ramdane, "KSU-IMR Mobile Robot Navigation Maps Building and Learning", Journal of Applied Mechanics and Materials, ISSN: 1662-7482, Vols. 789-790, pp. 717-722, Sep. 2015.
- J-36: Ebrahim Mattar ,Hessa Al-Junaid, "LMI Lyapunov Based Ts Fuzzy Modeling And Controller Synthesis For A Nonlinear Ball And Beam System," International Journal of Advance Computational Engineering and Networking (IJACEN), pp. 35-40, Volume-3, Issue-10, 2015.
- *J-37*: E. Mattar, "EEG Brainwaves for Robotics and Prosthesis Grasping and Motorization," International Journal of Materials, Mechanics and Manufacturing, pp. 196-172, Vol 5, Number 3, ISSN: 1793-8198, pp. 169-172, August 2017.
- J-38: E. Mattar, H. Al-Junaid and H. Al-Seddiqi, "PCA Based EEG Event Features Extraction for Robotics Dexterous Grasping," International Journal of Computing and Digital Systems, ISSN (2210-142X), International Journal of Computing and Digital Systems. 6, No.5, (Sep-2017), 2017.
- *J-39*: E. Mattar, H. Al-Junaid and H. Al-Seddiqi, "EEG Based Learning for Robotics Complex Grasping and Dexterous Manipulation, Refereed Book Chapter in Biomimetic Prosthetics, ISBN 978-953-51-5451-8, Book edited by: Ramana Vinjamuri, Stevens Institute of Technology, USA.,(Dec-2017), Nov. 2017.
- J-40: E. Mattar, K. AlMutib, M. AlSulaiman, and H. Ramdane, "Mobile Robot Neuro-fuzzy Navigation Based VSLAM Features Learning," International Journal of Computing and Digital Systems, Vol. 5, No. 6, December, 2017.
- *J-41*: Ebrahim A. Mattar and Hessa Al-Junaid, "Electroencephalography Based Dexterous Robotics Hand Grasping and Manipulation: A Short Review," Robotics and Automation Engineering Journal (RAEJ), volume 2, issue 2, Robot Autom Eng. J. 2(2): RAEJ.MS.ID.555583 (2018), March 2018.
- J-42: Ebrahim A. Mattar, Hessa Al-Junaid, Khalid N. Al-Mutib "Electroencephalography Features Extraction and Deep Patterns Analysis for Robotics Learning and Control through Brain-Computer Interface," accepted in Journal of Advances in Science, Technology and Engineering Systems (ASTESJ)-2021.
- J-43: G. Murad and E. Mattar, "On the Design of Robust Four Degree of Freedom Controllers for Linear Discrete-Time Systems," in IEEE Access, vol. 11, pp. 91028-91050, 2023, doi: 10.1109/ACCESS.2023.3307569.-2023.
- *J-44*: FATEMA A. SARHAN and Ebrahim Mattar, "Fake Accounts Detection in Online Social Networks using Hybrid Machine Learning Models," International Journal of Simulation Systems, Science and Technology, DOI 10.5013/IJSSST.a.24.02.02, ISSN: 1473-804x online, 1473-8031.
- J-45: FATEMA A. SARHAN and Ebrahim Mattar, "A Study on the Effects of U-Net Skip-Connections on Brain Tumor BraTS Dataset," International Journal of Simulation Systems, Science and Technology, DOI 10.5013/IJSSST.a.24.01.06, ISSN: 1473-804x online, 1473-8031.
- ${\it J-46: } \ \, \text{Jawaher Adel Albanki and Ebrahim A Mattar, "Classification of Brain Tumor Using CoAtNet Model", American Journal of Biomedical Science and Research, 2023 20(2). AJBSR.MS.ID.002687. DOI: 10.34297/AJBSR.2023.20.002687.$
- J-47: S M Masfequier Rahman Swapno, S. M. Nuruzzaman Nobel,Md Babul Islam, Pronaya Bhattacharya, and Ebrahim Mattar, "ViT-SENet-Tom: machine learning-based novel hybrid squeeze–excitation network and vision transformer framework for tomato fruits classification", International Journal of Neural Computing and Applications, 37, 6583–6600 (2025). https://doi.org/10.1007/s00521-025-10973-5.
- J-48: Amal H. Alharbi, Ebrahim Mattar, Sayed Elkenawy, and Mohamed E. Ghoneim, "Potato Leaf Disease Detection Using Deep Reinforcement Learning and the Ocotillo Optimization Algorithm," International Journal of Potato Research (2025), Springer, https://doi.org/10.1007/s11540-025-09941-2.

J-49: Rahul Priyadarshi, Ebrahim Mattar, Sandeep Chintham, Haneef Khan, Hussein Zangoti, Malik Alam, Ishan Budhiraja, Aditya Bhardwaj, Abhay Bindle, Pronaya Bhattacharya, and Pushan Dutta, "Elevating Connectivity and Security in Wireless Sensor Networks deployment through Innovative Key Selection Strategy for Smart Cities, "International Journal of Human-centric Computing and Information Sciences (2025) 15:55.

J-50: Saber Mohamed, Ebrahim Mattar, M Marwa, M El-Sayed, "Greylag Goose Optimization for Feature Selection and Hyperparameter Tuning in Chronic Kidney Disease Detection," International Journal of Intelligent Systems and Internet of Things, vol., no., 2025, pp. 152-190. DOI:https://doi.org/10.54216/JISIoT.170211.

J-51: Ahdi Hassan, Pushan Dutta, Subir Gupta, Ebrahim Mattar, and Satya Singh, "Emerging Technologies in Digital Manufacturing and Smart Factories", (Global Institute for Research Education and Scholarship, The Netherlands), Indexed in SCOPUS, Release Date December, 2023, Pages, 291 DOI: 10.4018/979-8-3693-0920-9.

J-52: Pushan Kumar Dutta, Subir Gupta, Ebrahim Mattar, and Satya Singh, and Ahdi Hassan "Human-Centered Approaches in Industry 5.0: Human-Machine Interaction, Virtual Reality Training, and Customer Sentiment Analysis," (Global Institute for Research Education and Scholarship, The Netherlands), Indexed In: SCOPUS Release Date: January, 2024—Copyright: © 2024—Pages: 369 DOI: 10.4018/979-8-3693-2647-3.

PUBLICATION LIST: Books, and Chapters of Books

(ii): Refereed Books/Chapters of Books:

ch-01: Al-Gallaf E., Allen A., and Warwick K., "Multi-fingered Robot Hands", in "Robotic Systems: Advanced Techniques and Applications (Intelligent Systems, Control and Automation: Science and Engineering)" Book, Chapter Seven, a Book Edited by: Prof. S.G. TZAFESTAS, PP. 543-551, ISBN 0-7923-1749-1, Kluwer Academic Publisher, 1991.

ch-02: Al-Gallaf E., "Robots, Mechanics of Perception and New Trends in Modern Industry," A Book Published by Arabian Establishment for Printing, Bahrain, 1999.

ch-03: Al-Gallaf E., "Intelligent Based Cartesian Object Mapping for Multi-Finger Robot Hand Control," a chapter in Book Titled as: "Focus on Robotics Research," Edited by Prof. John X. Liu, NOVA International Publishers, Binding: Hardcover, ISBN: 1-59454-594-4, 2005.

ch-04: Al-Gallaf E., "Transputer Neuro-Fuzzy Controlled Behavior-Based Mobile Robotics System," Chapter (15) in Edited Book of: Mobile Robots, Moving Intelligence, pp. 287-308, Edited by Prof. Jonas Buchli, ISBN 3-86611-284-X, December, 2006.

ch-05: Mattar E., "A Neural Network Based Visual Servo System: Learning Visual Kinematics of A Scene," Chapter in Book Under Title: (Neural Networks Applications), Published by Nova Science Publishers, Binding: Hardcover, Editor: Seoyun J. Kwon, ISBN: 978-1-61761-553-5, 2011.

ch-06: Mattar E., "A Neural Network Based Visual Servo System: Learning Visual Kinematics," Chapter in Book Under the Title: (New Developments in Artificial Neural Networks Research), Published by Nova Science Publishers, Editor: Robert W. Nelson, ISBN: 978-1-61324-286-5, 2011.

ch-07: Mattar E., "Dexterous Multi-finger Robotics Hands: A Way Forward for Intelligent And Skillful Manipulations," A New Complete Published Text Book, AMAZON: (Robotics Hands: A Way Forward for Intelligent And Skillful Manipulation). LAP LAMBERT Academic Publishing. ISBN-13: 978-3846501894, 2011.

ch-08: Mattar E., "Robotics Arm Visual Servo: Estimation of Arm-Space Kinematics Relations With Epipolar Geometry Robotic Systems", Chapter No. 10, in "Robotic Systems Applications, Control and Programming", ISBN 978-953-307-941-7, Published: February 3rd 2012.

ch-09: E. Mattar, H. Al-Junaid and H. Al-Seddiqi, "EEG Based Learning for Robotics Complex Grasping and Dexterous Manipulation, Refereed Book Chapter in Biomimetic Prosthetics, ISBN 978-953-51-5451-8, Book edited by: Ramana Vinjamuri, Stevens Institute of Technology, USA., (Dec-2017), Nov. 2017.

ch-10: E. Mattar, "Mobile Robot Feature-Based SLAM Behaviour Learning, and Navigation in Complex Spaces," A refereed Book Chapter, (Mobile Robots - Volume 1", ISBN 978-953-51-6702-0), Book edited by: Prof. Efren Gorrostieta Hurtado, Engineering Faculty of the Autonomous, University of Queretaro, Mexico, INTECH, November 2019

ch-11: Full Book: Ebrahim Mattar, "Bahrain Education History: 1919-2019, Full Book, 330 page, published officially during 2023.

ch-12: Full Book: Ebrahim Mattar, "Muharreq Cultural and History", Full Book, 330 page, published officially during 2023.

ch-13: Full Book: Ebrahim Mattar, "Diving and Pearl History", Full Book, 300 page, published officially during 2025.

PUBLICATION LIST: Conferences

(iii): Refereed Conferences Articles:

Conf-01: Al-Gallaf E., Allen A. and Warwick K., "Multi-fingered Robot Hands," Proceedings of the European Robotics and Intelligent Systems EURISCON-91, June1991, Corfu - Greece, 1991.

Conf-02: Al-Gallaf E., Allen A., and Warwick K., "Evaluation of a Direct Drive Approach in Multi-fingered Robotics Hands", IEE Colloquium Proceedings on Robot Actuators, pp. 7/1-7/4, October, London, UK, 1991.

Conf-03: Al-Gallaf E. and Warwick K., "Robot Hand Compliance Motion with Optimal Contact Forces, "Proceedings of the ICMA'94, International Conference on Machine Automation, 15-18 Feb. 1994, Tampere University of Technology, Tampere, Finland, 1994.

Conf-04: Al-Gallaf E. and Warwick K., "Optimal Manipulation Forces Distribution for Controlling Object Motion in a Four Fingered Robot Hand (Cybhand)," Proceedings of the IEE International Control Conference, CONTROL-94, pp. 555-560, Warwick University, UK, 1994.

Conf-05: Al-Gallaf E. and Warwick K., "CybHand: A Four Fingered Robot Hand and Singularities," IEEE Proceedings of the IMACS International Symposium on Signal Processing, Robotics and Neural Networks, pp. 590-593, May, Lille, France, 1994.

Conf-06: Al-Gallaf E. "Hybrid Control at Presence of Singularities in Multiple Contact Coordinated Manipulation by a Robot Hand," Proceedings of the 1st Bahrain International Conference on Computers in Industry, 6-8 Nov. 1995, pp. 286-306. Bahrain, 1995.

Conf-07: Al-Gallaf E., "Investigations of Industrial Environments and Robotics Involvement in Bahrain," Proceedings of the 1st Bahrain International Conference on Computers in Industry, 6-8 Nov. 1995, pp. 270-284, Bahrain, 1995.

Conf-08: Al-Gallaf E., "Neuromorphic Adaptation and Learning Using Fuzzy-Membership Function Based Neural Networks in Industrial Chemical Process," Proceedings of the 1st Bahrain International Conference on Computers in Industry, 6-8 Nov. 1995, pp. 2-20, Bahrain, 1995.

Conf-09: Al-Gallaf E. and Warwick K., "Fuzzy Membership Based Neural Employment in Visual Servoing and Manipulation by a Multi-Finger Robot Hand," Proceedings of the International ICSC Symposia on Intelligent Industrial Automation (IIA '96), March 1996, pp. 168-174, UK, 1996.

Conf-10: Al-Gallaf E. and Warwick K., "Acquiring Multi-Fingered Robot Hand Skills via Reinforcement Learning for Stiffness Control," Proceedings of the International ICSC Symposia on Intelligent Industrial Automation (IIA '96), March 1996, pp. 175-181, UK, 1996.

Conf-11: Al-Gallaf E. and Al-Mutiab K., "Visual Manipulation Based on Multi-Finger Robot Hand, "IEEE Proceedings of the 6th International Conference on Computing Systems: Theory and Applications, 3-5 Sept. 1996, Al-Askandaria, Egypt, 1996.

Conf-12: Al-Gallaf E. and Al-Ruwaihi K., "Remote Image Segmentation and Understanding via Artificial Convolution Neural Networks" Proceedings of the Middle East International GIS Conference and Workshops, October 19-21, Bahrain, 1998.

Conf-13: Al-Gallaf E. and Al-Ruwaihi K., "Fuzzy Remote Image Clustering" Proceedings of the Middle East International GIS Conference and Workshops, October 19-21, 1998, Bahrain, 1998.

Conf-14: Al-Gallaf E. and Murad G.,"A Digital H-inf Loop Shaping Controller for an Active Mass Driver System: A Benchmarks Problem in Controlling Buildings," Proceedings of the International American Control Congress: ACC-Publication, USA, 1998.

- Conf-15: Qamber I. and Al-Gallaf E., "Neural-Fuzzy Clustering for Anomalous Week Load Forecasting," Proceeding of the GCC CIGRE 10th Annual Symposium and the 5th Exhibition for Electrical Equipment's, pp. 50-64, Jeddah, KSA, November 10-11, 1999.
- Conf-16: Al-Gallaf E. "Neural Network Based Inverse Kinematics for Multi-Finger Hand Control," Proceedings of the IASTED International Conference in Neural Networks [NN'2000], pp. 82-87, Pittsburgh, Pennsylvania, USA, 2000.
- Conf-17: Al-Gallaf E. and Sultan A., "Neuro-Fuzzy Based Model Predictive Control," Proceedings of the IASTED International Conference in Modeling and Simulation [MS' 2000], pp. 276-282, Pittsburgh, Pennsylvania, USA, 2000.
- Conf-18: Al-Gallaf E., "Constrained Neuro-fuzzy Model Predictive Control", Proceedings of the Second International Conference on Computer in Industry, pp. 151-156, Bahrain, 2000.
- Conf-19: Al-Gallaf E., Qamber I., and Al-Jamea A., "Reliability Assessment of Evolutionary-Neural Load Predication for State of Bahrain", Proceedings of the 2nd International Conference on Computer in Industry, pp. 97-105, Bahrain, 2000.
- Conf-20: Al-Gallaf E., "New Era of Training and Continuing Education," Proceedings of the International Conference on Technical and Vocational Education, ICTVT-2000, 14-17 Nov, Malaysia, 2000.
- Conf-21: Al-Gallaf E., "GCC Countries and the Future Prospects of Continuing Education," Proceedings of the International Conference on Millennium Dawn on Training and Continuing Education, MDTCE-2001 pp. 555-562, April, Bahrain, 2001.
- Conf-22: Al-Ruwaihi K. and Al-Gallaf E., "Engineering Education in the New Millennium: What Should we Concentrate On?, The 6th Saudi Engineering Conference," KSA, 15-18, March 2002.
- Conf-23: Al-Gallaf E. and Al-Junaid H., "Hinf Robust Fuzzy Control for Nonlinear Dynamic Systems", Proceedings of the ICAIA'2002 10th International Conference on Artificial Intelligence Applications, Cairo, Feb 6-9, 2002.
- Conf-24: Al-Gallaf E. and Al-Junaid H., "Robust Fuzzy Control for Nonlinear Parametric Uncertainty Systems", Proceedings of the 2nd Arabian Technology and Sciences Conference, SRO-2002, 24-27, UAE, March 2002.
- Conf-25: Al-Gallaf E., "The Effect of Communication, and Information Technology on the Quality, Competence and Effectiveness of Technician", Regional Conference on Engineering Technician Competence and Effectiveness Conference and Exhibition, 26-27 April, Kingdom of Bahrain, 2003.
- Conf-26: Al-Gallaf E., "Role of University-Industry Relation in Bahrain in Enhancing Technology Transfer, "Proceedings of the First Middle East Conference on Technology Transfer, 22-23, September, Kingdom of Bahrain, 2003.
- Conf-27: Al-Gallaf E., "Neuro-Fuzzy Based Takagi-Sugeno Clustering And Modeling of Nonlinear System," Proceedings of the third International Arab Conference on Information Technology (ACIT'2003), 23-25 December, Egypt, 2003.
- Conf-28: Al-Gallaf E., "LMI Based Robust Fuzzy Stabilization of a Nonlinear Dynamic System", IASTED 23rd International conference on Modeling, Identification and Control (MIC 2004), February 23-25, pp. 250-25, Grindelwald, Switzerland, 2004.
- Conf-29: Al-Gallaf E., "Neuro-Fuzzy Based Takagi-Sugeno Modeling of Nonlinear Multivariable Antenna Dynamic System", IASTED 23rd International conference on "MODELING, IDENTIFICATION, AND CONTROL (MIC 2004), February 23-25, pp. 241-249, Grindelwald, Switzerland, 2004.
- Conf-30: Al-Mansoori W., Al-Gallaf E., and A. Issa, "Neuro-fuzzy Output Time Delay Model for Short Channel CMOS Inverter", 2nd IEEE Conference (GCC), Bahrain 23-26, 2004.
- Conf-31: Al-Gallaf E. and Al Mutib K., "Multi-finger Robot Hand Neuro-fuzzy Mapping and Control," Proceedings of the fourth International Arab Conference on Information Technology (ACIT'2004), December 12-15, Universit Mentouri, Algeria, 2004.
- Conf-32: Ebrahim Al-Gallaf and Khalid Al-Mutib, "Neuro-Fuzzy System Based Dexterous Robot Hand Task Space Manipulation", IEEE Sponsored (SETIT 2005) 3rd International Conference: Sciences of Electronic, Technologies of Information and Telecommunications, March 27-31, 2005, TUNISIA.

- Conf-33: Al-Gallaf E., "Robotics System Optimal Task Control: Neuro-Inverse Kinematics Approach", IEEE 2006, IEEE GCC Conference, Manama-Bahrain, March 21-23, 2006.
- Conf-34: Al-Gallaf E., "Intelligent Nonlinear Predictive Control", IEEE 2006, IEEE GCC Conference, Manama-Bahrain, March 21-23 ,2006.
- Conf-35: Al-Gallaf E., "Role of University Industry Relation in Bahrain in Enhancing Technology Transfer", Proceedings of 1st University of Bahrain Scientific Research Conference, Bahrain, April 28-29, 2006.
- Conf-36: Al-Gallaf E., "Measurement of an Image Principal Components Understanding Via Artificial Neural Networks", 3rd Middle East Metrology Conference and Exhibition Measurement and Instrumentation, 2006, 29-31 May 2006, Bahrain.
- Conf-37: Al-Gallaf E., "Nonlinear System State Measurement in Presence of Disturbance", 3rd Middle East Metrology Conference and Exhibition -Measurement and Instrumentation, 2006, 29-31 May 2006, Bahrain.
- Conf-38: Mehmet Akbaba, Amin M. Sultan, and Al-Gallaf E., "Detailed Transient Analysis of Self Excited Induction Generator Feeding Induction Motor", XVII International Conference on Electrical Machines, September 2-5, 2006, Greece.
- Conf-39: E. Mattar, "Robotics Neural Net Grasping System, a Dialogue Article," for the IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO'07), at the Microelectronics and Information Systems Research Center National Chiao Tung University, Hsinchu, Taiwan, December 9-11, 2007.
- Conf-40: Al-Gallaf E. and Akbaba M., "LMI- Intelligent Modeling and Control of Highly Nonlinear Electrical System," Proceedings of the IET International Conference on Intelligent Systems (ICIS-2008), 1-3, December 2008, Kingdom of Bahrain.
- Conf-41: M. A Hameed and Al-Gallaf E., "Iris Recognition: Principal Component Analysis Approach," Proceedings of the IET International Conference on Intelligent Systems (ICIS-2008), 1-3, December 2008, Kingdom of Bahrain.
- Conf-42: Al-Gallaf E., "Funding Scientific Research: International Experience and Studies", Proceedings of 2nd University of Bahrain Scientific Research Conference, 2007, March 28-29, (2007), Kingdom of Bahrain. (University of Bahrain Local Forum).
- Conf-43: E. Al-Gallaf, "Nonlinear Model Predictive Control Synthesis Via Artificial Neural Networks State Identification," International Conference on Computer Modeling and Simulation (ICCMS-2009), February 20-22,(2009), Macau, China.
- Conf-44: E. Al-Gallaf, "Intelligent Nonlinear Predictive Control State Identification," International Conference on Computer Modeling and Simulation (ICCMS-2009), Organized by the International Association of Computer Science and Information Technology, Macau, China, February 20-22, (2009)
- Conf-45: E. Al-Gallaf and H. Al-Junaid, "Hinf Robust Control for Nonlinear Parametric Uncertain Dynamic Systems Fuzzy Gain-Scheduling", (EPSCI-CON 2010), IEEE International Conference on Power, Signals, Control and Computation, January 04-06, 2010, Thrissur, INDIA.
- Conf-46: E. Al-Gallaf and A. Sultan, "Model Predictive Control Technique ANN Nonlinear Plants Modeling and Controller Synthesis", (EPSCI-CON 2010), IEEE International Conference on Power, Signals, Control and Computation, January 04-06, 2010, Thrissur, INDIA.
- Conf-47: Al-Gallaf E. and Al-Mutib K., "ANN Dexterous Robotics Hand Optimal Control Methodology Grasping and Manipulation Forces Optimization," The Fifteenth International Symposium On Artificial Life And Robotics (AROB 15th '10) AROB 15th ANNIVERSARY, February 4-6, 2010, B-Con Plaza, Beppu, Oita, JAPAN.
- Conf-48: E. Mattar (Al-Gallaf), [2010] "Epipolar-Kinematics Relations Estimation, Neural Approximation For Robotics Closed Loop Visual Servo System", (ICCAE-2010), A Paper presented and Published in the Proceedings of the IEEE 2nd International Conference on Computer and Automation Engineering (ICCAE-2010), 26 28, February 2010, Singapore.
- Conf-49: Mattar E., Al Mutib K, and Hamdan H., "Bio-Inspired Transputer Based-Fuzzy Mobile Robot," Presented and published manuscript at the (Bionetics 2010), 5th International ICST Conference on Bio-Inspired Models of Network, Information, and Computing Systems, December 1-3, 2010 Boston, MA, USA.

- Conf-50: Mattar E. Al-Gallaf, and H. Al-Junaid, "Hinf Robust Stabilization of Nonlinear System: Fuzzy System Approach", (ICCAE-2010), A Paper presented and Published in the Proceedings of the IEEE 2nd International Conference on Computer and Automation Engineering (ICCAE-2010), 26 28, February 2010, Singapore.
- Conf-51: Mattar E., "A Learning Rule-Based Robotics Hand Optimal Force Closure," The Second International Conference on Computational Intelligence, Communication Systems and Networks CICSyN-2009, Proceedings of the IEEE Computer Society Publication, 28-30 July 2010, Liverpool, UK.
- Conf-52: Mattar E., and K. Al Mutib, "Bio-Inspired Robotics Hands: A Work in Progress," Presented And Published manuscript in the Proceedings at the (Bionetics 2010), 5th International ICST Conference on Bio-Inspired Models of Network, Information, and Computing Systems, December 1-3, 2010 Boston, MA, USA.
- Conf-53: Al Mutib K., Al Sulaiman M., Mathkour H., and Mattar E., "D Lite Based Real-Time Multi-Agent Path Planning in Dynamic Environments," Proceedings IEEE on CIMSim-2011, The Third International Conference on Computational Intelligence, Modeling and Simulation, Print ISBN: 978-1-4577-1797-0, 20 22 September 2011, (2011), Malaysia.
- Conf-54: Al Mutib K. and Mattar E., "Neuro-fuzzy Controlled Autonomous Mobile Robotics System," 13th International Conference on Computer Modeling and Simulation (UKSim), 2011 UK-Sim, March 30 2011-April 1 2011, ISBN: 978-1-61284-705-4, pp. 1-7, Cambridge, UK.
- Conf-55: Mattar E., "Dexterous Robotics Hands: ANN Based Artificial Muscles Control," 13th International Conference on Computer Modeling and Simulation (UKSim), 2011 UK-Sim, March 30 2011 April 1 2011, Print ISBN: 978-1-61284-705-4, pp. 224-229, Cambridge, UK.
- Conf-56: Mattar E., "Financing Scientific Research: International Practice," Accepted manuscript for the (ICSR 2011), First Gulf International Conference on Scientific Research, Bahrain University, April 25-26, 2011, Kingdom of Bahrain.
- Conf-57: Mattar E. and Al Mutib K., "Synthesizing Fuzzy Based Model Predictive Controller," Proceedings of IEEE on CIMSim2011, The Third International Conference on Computational Intelligence, Modeling and Simulation, Print ISBN: 978-1-4577-1797-0, 20-22 September 2011, Malaysia.
- Conf-58: Mattar E. and Al Mutib K., "Fuzzy Gain-Scheduling Nonlinear Parametric Uncertain System ," Proceedings of IEEE on CIMSim2011, The Third International Conference on Computational Intelligence, Modeling and Simulation, Print ISBN: 978-1-4577-1797-0, 20-22 September 2011, Malaysia.
- Conf-59: Al Mutib K., Al Sulaiman M., Mathkour H., Mattar E., and Ramdane H., "KSU-IMR; An Intelligent Mobile Robotics System: Active Stereo Vision Path Planning Navigation For Unstructured Environments," Presented at The Twenty-Fourth International Conference on Computer Applications in Industry and Engineering (CAINE-2011), November 16-18, 2011, Honolulu, Hawaii, USA.
- Conf-60: Mattar E., "Biomimetic Dexterous Hands: Human Like Multi-fingered Robotics Hand Control," Proceedings of IEEE Computer Society, 14th International Conference on Computer Modeling And Simulation (UKSim), 2012 UK-Sim, Paper ID: 1569568861, 28-30 March 2012, 978-0-7695-4682-7/12, 2012 IEEE University of Cambridge, Cambridge, UK.
- Conf-61: K. Al-Mutib, M. Al Sulaiman, Hedjar Ramdane, M. M. Emaduddin, And E. A. Mattar., "Active Stereo Vision for Mobile Robot Localization and Mapping Path Planning," Proceedings of IEEE Computer Society, 14th International Conference on Computer Modeling and Simulation (UKSim), 2012 UK-Sim, Paper ID: 1569571081, 28-30 March 2012, 978-0-7695-4682-7/12, 2012 IEEE, University of Cambridge, Cambridge, UK.
- Conf-62: Mattar E., "Technical Education in Bahrain: Plans and Directions," ALECSO Regional Meeting in Sudan for (Arabian for Education, Culture and Sciences Organization, the ALECSO), Sudan, 9-12 of April 2012, Sudan.
- Conf-63: K. Al-Mutib, E. A. Mattar, M. Al Sulaiman, H. Ramdane, and M. Emaduddin, "Neural Net Robotics Visual Servo: Learning the Epipolar Geometry," Proceedings of (WORLDCOMP'12 The 2012 World Congress in Computer Science, Computer Engineering, and Applied Computing), The 2012 International Conference on Artificial Intelligence, LAs Vegas, Navada, July 16-19. ICAI'12, 2012, USA.
- Conf-64: M. Emaduddin, K. Al-Mutib, M. Al Sulaiman, H. Ramdane, and E. Mattar, "Accurate Floor Detection and Segmentation for Indoor Navigation Using RGB+D And Stereo Cameras," Proceedings of (WORLDCOMP'12 The 2012 World Congress in Computer Science, Computer Engineering, and Applied Computing). The 16th International Conference on Image Processing, Computer Vision, and Pattern Recognition (IPCV'12: July 16-19, 2012, USA), LAs

- Vegas, Navada, July 16-19. ICAI'12, 2012, USA.
- Conf-65: K. Mutib, M. Emaduddin, M. Alsulaiman, H. Ramdane, and E. Mattar, "Motion Periodicity based Pedestrian Detection and Particle Filter based Pedestrian Tracking using Stereo Vision Camera," IEEE Sponsored Conference, and Proceedings of 2012 19th International Conference on Mechatronics and Machine Vision in Practice (M2VIP), pp. 37-42, November 28-30, AUT University Campus, Auckland. Proceedings of the IEEE, Xplore, 978-1-4673-1643-9, New Zealand.
- Conf-66: M. Emaduddin, K. Al-Mutib, M. Al Sulaiman, H. Ramdane, and E. Mattar, "Motion Periodicity based Pedestrian Detection and Tracking using Stereo Vision Camera," Proceedings of (CATA-2013), 978-1-880843-90-1 / ISCA CATA / March 2013, pp. 45-50, March 4-6, Honolulu, Hawaii, USA, 2013, Hawaii, USA.
- Conf-67: K. Al Mutib, M. Al Sulaiman, E. Mattar, H. Ramdane And Muhammad Emad AL-Dean, "Neural Network Vision-Based Visual Servoing And Navigation for KSU-IMR Mobile Robot Using Epipolar Geometry," Proceedings of the International Conference on Soft Computing And Software Engineering 2013 (SCSE'13). SCSE 2013 held on March 1-3, 2013, San Francisco State University, California, Chaired by Prof. Lotfi A. Zadeh, USA.
- Conf-68: E. Mattar, "eGRASP: A MATLAB Based Comprehensive Dexterous Robotic Hand Modeling And Simulation Environment," Proceedings of the IEEE 2013 UKSim 15th International Conference on Computer Modeling and Simulation, 10-12 April 2013, pp. 254, 259, 978-0-7695-4994-1/13, 2013 IEEE, UK, 2013.
- Conf-69: K. Al-Mutib, N. Adamali Shah, and E. Mattar, "Performance Analysis of Fuzzy Logic And PID Controller for PM DC Motor Drive," Proceedings of the 15th International Conference on Artificial Intelligence, July 22-25, 2013, Las Vegas, USA, 2013.
- Conf-70: M. Algabri, K. Al-Mutib, M. Alsulaiman, H. Ramdane, M. Emaduddin and E. Mattar, "Mobile Robot Navigation Using Neuro-fuzzy System," Proceedings of the 6th World Summit on the Knowledge Society, 19-21, June 2013, Aveiro, Portugal, 2013.
- Conf-71: M. Algabri, K. Al-Mutib, M. Alsulaiman, H. Ramdane, M. Emaduddin and E. Mattar, "Mobile Robot Navigation and Obstacle-avoidance Using Neuro-fuzzy System in Unknown Environment," Proceedings of the CAINE 2013, 26th International Conference on Computer Applications in Industry and Engineering, September 25-27, 2013, California, USA.
- Conf-72: M. Faisal, K. Al-Mutib, R. Hedjar, H. Mathkour, M. Alsulaiman, and E. Mattar, "Multi Modules Fuzzy Logic for Mobile Robots Navigation and Obstacle Avoidance in Unknown Indoor Dynamic Environment", SCI 2013, Proceedings of the 2013 International Conference on Systems, Control and Informatics, September 28-30, Venice, Italy 2013.
- Conf-73: E. Mattar, K. Al-Mutib, M. Al Sulaiman, H. Ramdane, M. Emaduddin, "KSU-IMR Occupancy Grids and Stereo Vision SLAM Navigation: Neuro Occupancy Mapping", (Invited Keynote Lecture), and in Proceedings of EPSCICON-2014, Thrissur, 8-10 January, India.
- Conf-74: E. Mattar, K. Al-Mutib, M. Alsulaiman, H. Ramdane, M. Emaduddin, "A Survey: Intelligent Based Mobile Robots Stereo Vision Maps Synthesis and Learning Methodologies," IEEE Proceedings of 2014 Fifth International Conference on Intelligent Systems, Modeling and Simulation, 2014 IEEE DOI 10.1109/ISMS.2014.159, pp. 93-98, Malaysia 2014.
- Conf-75: K. Almutib, M. Emaduddin, M. Alsulaiman, H. Ramdane and E. Mattar, "Reliable Multi-baseline Stereovision filter for Navigation in Unknown Indoor Environments," BICoB-2014, 6th International Conference on Bioinformatics and Computational Biology (BICoB), March 24-26, 2014 Las Vegas, Nevada (In conjunction with CATA-2014), USA.
- Conf-76: E. Mattar, "PCA Learning for Non-Brain Waves-Controlled Robotic Hand (Prosthesis): Grasp Stabilization and Control", Proceedings of the IEEE 2014 UKSim 16th, International Conference on Computer Modeling and Simulation, 26-28 March 2014, 2014-IEEE, UK, 2014.
- Conf-77: E. Mattar, "Robotics Innovation: Motivation to Research and Capitalize on Fast Emerging Market", UoB IS Forum IS Forum: Information Systems in Bahrain, Toward a Knowledge Society, Wed, 21st May 2014. University of Bahrain Local Forum.
- Conf-78: E. Mattar, "Enhancing Learning Process through Engagement with Professional Societies: University of Bahrain Practice", UoB College of Engineering 2014 Symposium, University of Bahrain 5th of June 2014, Bahrain.

- Conf-79: K. Al Mutib, E. Mattar, M. AlSulaiman, H. Ramdane, "PCA Based Mobile Robot Navigation and Mapping Intelligence," Proceedings of ISCA 27th International Conference on Computer Applications in Industry and Engineering (CAINE-2014), October 13-15, 2014, New Orleans, USA.
- Conf-80: E. Mattar, K. Al Mutib, M. AlSulaiman, H. Ramdane, "KSU-IMR Mobile Robot Navigation Maps Building and Learning," Proceedings of 2014 International Conference on Mechatronics and Intelligent Manufacturing (ICMIM 2014), UAE, December 2014.
- Conf-81: E. Mattar, "Neural Net Control of High Nonlinear 2-DOF Nonlinear Robotic Arm," Proceedings of 2014 International Conference on Mechatronics, Intelligent Manufacturing, ICMIM 2014, UAE, December 2014.
- Conf-82: E. Mattar, "Cognition Learning: Brain-Wave for Robotic Grasping and Dexterity Enhancement," Proceedings of the 2014 (IEEE-ROBIO2014), IEEE International Conference on Robotics and Biomimetics, December 5-10, 2014, Bali, Indonesia.
- Conf-83: E. Mattar, K. Al Mutib, M. AlSulaiman, H. Ramdane, "Stereo Vision SLAM Based Indoor Autonomous Mobile Robot Navigation," Proceedings of the 2014 (IEEE-ROBIO2014), IEEE International Conference on Robotics and Biomimetics, December 5-10, 2014, Bali, Indonesia.
- Conf-84: K. Al-Mutiba, E. Mattar, and M. Alsulaiman, "Implementation of Fuzzy Decision Based Mobile Robot Navigation using Stereo Vision," 2015 International Conference on Soft Computing and Software Engineering (SCSE'15), University of California, Berkeley, USA, 5-6 March 2015.
- Conf-85: E. Mattar, "Neural Net Control of High Nonlinear 2-DOF Nonlinear Robotic Arm," Selected, peer reviewed papers from the 2015 The 5th International Workshop on Computer Science and Engineering-Information Processing and Control Engineering (WCSE 2015-IPCE), April 15-17, 2015, Moscow, Russia.
- Conf-86: E. Mattar, "Learning Occupancy Features and Characterizations of Mobile Robot Stereo-Vision Based SLAM Navigation," The College of Science 7th, Scientific Research Forum, 13-14 April 2015, University of Bahrain, 2015.
- Conf-87: E. Mattar, "Learning Occupancy Features and Characterizations of Mobile Robot Stereo-Vision Based SLAM Navigation," The College of Science 7th, Scientific Research Forum, 13-14 April 2015, University of Bahrain, 2015.
- Conf-88: E. Mattar, and H. Al-Junaid, "LMI Lyapunov Based TS Fuzzy Modeling and Controller Synthesis for a Nonlinear Ball and Beam System," Proceedings of ISER 4th International Conference, August 2015, ISBN:978-93-85465-78-9,2015.
- Conf-89: E. Mattar and K. Al-Mutib, "EEG Complex Grasping Patterns Recognition for BMI Robotic and Prosthesis Motion Control," Invited Talk and Proceedings of the IET Michael Faraday International Summit: MFIIS-2015, September 21-13, 2015, Kolkata, India.
- Conf-90: Khalid Al Mutib, Ebrahim A. Mattar, and Abdulla Al Mutib, "Learning Grasping Optimality with EEG Hand Recordings: BMI for Robotic-Prosthetic Motion Control", in proceedings of 28th International Conference on Computer Applications in Industry and Engineering, CAINE 2015, October 12-14, 2015, Harbor Island, San Diego, California, USA.
- Conf-91: E. Mattar, "EEG Waves for Robotics and Prosthesis Grasping and Motorization," (Invited Keynote Lecture), Presented at ICKEA 2015, and in Proceedings of International Conference on Knowledge Engineering and Applications (ICKEA 2015), UAE, 12-13 November 2015.
- Conf-92: E. Mattar and K. Al-Mutib, "Understanding of Metric-Topological Maps for Mobile Robot Navigation," (IEEE-ROBIO2015) Proceedings of the 2015 IEEE Conference on Robotics and Biomimetics Zhuhai, China, December 6-9, 2015.
- Conf-93: E. Mattar, H. Al-Junaid, "Fuzzy C-Means Classification of Electroencephalography (EEG) Waves for Robotic System Time Events and Control," Conference: The 14th Pacific Rim International Conference on Artificial Intelligence, at (PRICAI 2016), Thailand, Volume: 1, ISBN 978-616-92700-1-0, 22-26 August 2016.
- Conf-94: E. Mattar, and A. Bu Hamood, "Development of Fuzzy-Decision Based Building Energy Preservation and Management System", A paper presented during (WREC17), the 17th World Renewable Energy Congress, 4-6 December 2016, Crowne Plaza, Kingdom of Bahrain.

Conf-95: E. Mattar, K. AlMutib, M. AlSulaiman, and H. Ramdane, "Mobile Robot Neuro-fuzzy Navigation Based VSLAM Features Learning," Proceedings of the 9th Conference and Exhibition (2017 9th IEEE-GCC Conference and Exhibition (GCCCE)), 9-11 May 2017, 978-1-5386-2756-3/17/2017 IEEE, pp. 151-156, Bahrain, 2017.

Conf-96: E. Mattar, "Machine Intelligence Based Living and Behavior Learning for Renewable Energy Management in Buildings", presented at the (Bahrain-Shanghai Renewable Energy Conference, One Belt One Road Initiative), University of Bahrain, 13-14 May 2017, Kingdom of Bahrain, 2017.

Conf-97: E. Mattar, "Machine Learning Tools Based EEG Decoding and Understanding for Limbs Movements," International Conference for Assistive Technology (TECHNO NO DISABILITY), 3-5 December, 2017.

Conf-98: E. Mattar and H. AL-Junaid, "Machine Learning for Electroencephalography Decoding and Robotics Dexterous Hands Movement", IEEE Explore, proceeding of the EPSCICON 2018, the 4th International Conference on Power, Signals, Control, and Computation, 6-10th January 2018, Vidya Academy of Science and Technology, Thrissur, Kerala, India.

Conf-99: A. M. Naeem, M. Hussain, E. Mattar, "Classification Based Decoding and Understanding of Eye Electroencephalography Movements for Robotics Application," IET Smart Cities Symposium Proceedings, SCS-2018, April 22-23, Bahrain 2018.

Conf-100: E. Mattar and H. AL-Junaid, "Manipulation Related EEG Brainwave Feature Extraction and Events Recognition for Robotics Learning Applications," Proceedings of the 2018 IEEE International Conference on Robotics and Biomimetics, ROBIO-2018, December 12-15, 2018, pp. 2051-2056, Kuala Lumpur, Malaysia.

Conf-101: E. Mattar, "Robotics Innovation, and to Capitalize on Fast Emerging Market", Paper appeared in the proceedings of the International Conference on Fourth Industrial Revolution 19 - 21 February, Bahrain 2019.

Conf-102: Khalid Al-Mutib and Ebrahim, "Robotics Research in the Middle East: A Regional Survey, and Future Prospects," Conference: 25 - 26 MARCH 2019, JUBAIL INDUSTRIAL CITY KINGDOM OF SAUDI ARABIA, 25-26 March 2019, KSA.

Conf-103: M. Sallout and E. Mattar, "Electroencephalography adaptive classification and decoding techniques," 2nd Smart Cities Symposium (SCS 2019), 2019, pp. 1-6, doi: 10.1049/cp.2019.0216, IET Proceedings, 24-26 March 2019, Polymin

Conf-104: E. A. Mattar, A. H. Alhamad, M. A. Elhawy, A. Khalid and H. N. Alshomali, "Electroencephalography synthesis of hand movement: Events features detection, classification, for robotics applications," 2nd Smart Cities Symposium (SCS 2019), 2019, pp. 1-6, doi: 10.1049/cp.2019.0211, IET Proceedings, 24-26 March 2019, Bahrain.

Conf-105: Ebrahim Mattar, Hessa Al-Junaid, Khalid N. Al-Mutib "Electroencephalography Features Extraction and Deep Patterns Analysis for Robotics Learning and Control through Brain-Computer Interface," 3rd ICT - 4th Edition, Bahrain.

Conf-106: Ebrahim Mattar, "AI for Social Applications," 2nd Int. Conference for Excellence of the Social Works," 5-7 October 2019, Bahrain.

Conf-107: Ebrahim Mattar, "Robotics Surveillance and Security Applications: Surveying Recent Trends and Directions," The 9th ASIS Middle East 2019 Conference and Exhibition, Nov. 2019, Bahrain Conf-108 (2019).

Conf-108: Mohammad Sallout and Ebrahim Mattar, "Enhanced EEG Classification Accuracy Personal-based for Smart Healthcare Applications," Future Smart Cities (FSC) -2nd Edition 05, Nov - 07, Nov 2019, Kuala Lumpur, Malaysia.

Conf-109: Ebrahim Mattar, Hessa Al-Junaid, Khalid N. Al-Mutib, "EEG Events Patterns Recognition for Robotics Reasoning and Decision Enhancement," 16th IEEE ROBIO 2019, International Conference on Robotics and Biomimetics), 06-08 December 2019, Dali, Yunnan, China.

Conf-110: Maram Saleh Alfaraj, Ebrahim Mattar, "Artificial Intelligence for Crowd Detection System: A Survey," the 4th IET SCS Symposium 2021, November 21-23, 2021.

Conf-111: E A Mattar and H J Al-Junaid, "Electroencephalography Fuzzy Based Classification for Robotics Learning Applications," Robotics Congress 2021, I-World Summit on Robotics, June 08-09, 2020.

- Conf-112: Ebrahim Mattar, Iffat Rashid, and Marriam Rahat, "SVM Classification Based Fuzzy Understanding of Eye Electroencephalography Movements for Robotics Applications," Proceedings of the 3rd SMART CITIES SYM-POSIUM, IET-Inspec indexed, 21-23 September 2020.
- Conf-113: Mohammed Sallout and Ebrahim Mattar, "EEG-based Classification of Visually Evoked Emotions using Multiscale Entropy Features," Proceedings of the 3rd SMART CITIES SYMPOSIUM, IET-Inspec indexed, 21-23 September 2020.
- Conf-114: E A Mattar, "Electroencephalography Fuzzy Based Classification for Robotics Learning Applications," Robotics Congress 2021, II-World Summit on Robotics, UAE, February 24, 2021.
- Conf-115: H Aljamea and E A Mattar, "Special Topics in Artificial Intelligence Music Transcription using CNN Neural Networks," the 4th IET SCS Symposium 2021, IET-Inspec indexed, November 21-23, 2021.
- Conf-116: Ebrahim Mattar, Hessa Al-Junaid, Khalid N. Al-Mutib, "EEG Events Patterns Recognition for Robotics Reasoning and Decision Enhancement," 16th IEEE ROBIO 2019, International Conference on Robotics and Biomimetics), 06-08 December 2019, Dali, Yunnan, China.
- Conf-117: Ebrahim Mattar and H J Al-Junaid, "Electroencephalography Fuzzy Based Classification for Robotics Learning Applications," Robotics Congress 2021, I-World Summit on Robotics, June 08-09, 2020.
- Conf-118: Ebrahim Mattar, Iffat Rashid, and Marriam Rahat, "SVM Classification Based Fuzzy Understanding of Eye Electroencephalography Movements for Robotics Applications," Proceedings of the 3rd SMART CITIES SYM-POSIUM, IET-Inspec indexed, 21-23 September 2020.
- Conf-119: Mohammed Sallout and Ebrahim Mattar, "EEG-based Classification of Visually Evoked Emotions using Multiscale Entropy Features," Proceedings of the 3rd SMART CITIES SYMPOSIUM, IET-Inspec indexed, 21-23 September 2020.
- Conf-120: Ebrahim Mattar, "Electroencephalography Fuzzy Based Classification for Robotics Learning Applications," Robotics Congress 2021, II-World Summit on Robotics, UAE, February 24, 2021.
- Conf-121: Fatema A. Sarhan and Ebrahim Mattar, "Fake Accounts Detection in Online Social Networks using Hybrid Machine Learning Models," UKSim-AMSS 25th International Conference on Modelling and Simulation, Cambridge University(Emmanuel College),12-14 April 2023.
- Conf-122: A. Almubarak and E. A. Mattar, "Implementation of islanding protection system into Simulink model," 7th IET Smart Cities Symposium (SCS 2023), Conference, Bahrain, 2023, pp. 667-671, doi: 10.1049/icp.2024.1036.
- Conf-123: A. Almubarak and E. A. Mattar, "Islanding detection classification using artificial neural networks," 7th IET Smart Cities Symposium (SCS 2023), Conference, Bahrain, 2023, pp. 667-671, doi: 10.1049/icp.2024.1036.
- Conf-124: Albanki Jawaher and Ebrahim Mattar, "Fake Accounts Detection in Online Social Networks using Hybrid Machine Learning Models," UKSim-AMSS 25th International Conference on Modelling and Simulation, Cambridge University(Emmanuel College),12-14 April 2023.
- Conf-125: Ebrahim Mattar, "Electroencephalography for Enhancing Robotics Learning: CNN Convolutional Neural Network Approach," UKSim-AMSS 25th International Conference on Modelling and Simulation, Cambridge University(Emmanuel College),12-14 April 2023.
- Conf-126: P. Bhattacharya, E. A. Mattar, P. Kumar Dutta, W. Gong and J. J. P. C. Rodrigues, "LLM-Twins: A Large Language Model driven trusted Cyber Twin framework for Healthcare 5.0 ecosystems," 2025 10th International Conference on Smart and Sustainable Technologies (SpliTech), Bol and Split, Croatia, 2025, pp. 1-6, doi: 10.23919/SpliTech65624.2025.11091664.
- Conf-127: E. A. Mattar, P. Bhattacharya, P. K. Dutta and J. J. P. C. Rodrigues, "LLM-FaaS: A Secured Large Language Model assisted Fog-as-a-Service Framework," 2025 10th International Conference on Smart and Sustainable Technologies (SpliTech), Bol and Split, Croatia, 2025, pp. 1-6, doi: 10.23919/SpliTech65624.2025.11091727.
- Conf-128: E. A. Mattar, P. Kumar Dutta, P. Bhattacharya and J. J. P. C. Rodrigues, "Edge-Cloud Latency Optimization: A Priority-Based Scheduling Framework with Dynamic VM Allocation," 2025 10th International Conference on Smart and Sustainable Technologies (SpliTech), Bol and Split, Croatia, 2025, pp. 1-5, doi: 10.23919/SpliTech65624.2025.11091697.

PUBLICATION LIST: (iv): Publications: Technical Reports for Projects: Technical Reports

Tech-01: PROJECT REPORT: Energy Saving in Bahrain: Technical Report submitted to the University of Bahrain and the UN-DEP, Bahrain. Author: Qamber I. and Mattar E., 1998.

Tech-02: PROJECT REPORT: Energy Saving and Intelligent House Automation: Study Report submitted to the University of Bahrain, Deanship for Scientific Research. Author: Mattar E., 1998.

Tech-03: TECHNICAL REPORT: Building UoB 3-DOF Robotic Arm: Author: Mattar E., 1999.

Tech-04: PROJECT REPORT: Bahrain Social-Cultural and Educational-Training Dimensions in Flattering Job Creation Educational, Cultural and Social: Dealings Prospects with Restructuring Policies. Technical Report of DARDEN School of Business Visit. Sponsorship: Author: Mattar E., Bosera A, Al-Hashimi A. and Amin K., 1999.

Tech-05: REPORT: Darden Gulf Executive Program: Gulf Executive Program in Management in Darden, Technical Report of DARDEN School of Business visit submitted to University of Bahrain Council Author: Mattar E., 2000.

Tech-06: TECHNICAL REPORT: Artificial Neural Network Face Recognition Via Principle Components Analysis. Technical Report submitted to University of Bahrain Deanship of Scientific Research Sponsorship: Author: Mattar E. and Al-Ruwihi K., 2000.

Tech-07: TECHNICAL REPORT: ANN for Stock Market Predication. Technical Report submitted to University of Bahrain Deanship of Scientific Research Sponsorship: Author: Mutawe S. and Mattar E., 2001.

Tech-08: PROJECT REPORT: Engineering Job Creation in Bahrain Over the Coming 10 Years, Technical Report submitted to the Deanship of Scientific Research, University of Bahrain. Author: Mattar E., 2000.

Tech-09: TECHNICAL REPORT: Designing a Robotics Arm System for Science Center, for Educational Services. Author: Mattar E., 2000.

Tech-10: PROJECT REPORT: Neural Network Financial Stock Market Forecasting, Technical Report submitted to Deanship of Scientific Research Author: Mattar E., and Al-Mutawia S., 1998.

Tech-11: TECHNICAL REPORT: Modeling of Materials Internal Physical Parameters. Technical Report submitted to Bahrain Welding Wire Products Sponsored by Bahrain Welding Wire Products, Bahrain. Author: Mattar E., 2007

Tech-12: PROJECT REPORT: Intelligent Mobile Robotics System: Intelligent Interaction Capabilities With an Active Stereo Vision-Path Planning Navigation in Unstructured Hazardous Environments, Sponsored by King A. Aziz City For Science and Technology, Kingdom of Saudi Arabia. Author: Al Mutib K., Mattar E. Ramdane H., Al Sulaiman M., Abdsemed F., Mathkour H. and Arafah M., 2010.

Tech-13: PROJECT REPORT: Face Recognition System Sponsored by King A. Aziz City For Science and Technology, Kingdom of Saudi Arabia Author: Al Mutib K., Mattar E. Ramdane H., Al Sulaiman M., Abdsemed F., Mathkour H. and Arafah M., 2008.

Tech-14: PROJECT REPORT: High Speed Vehicle Detection on Bahrain Highways. Technical Report submitted to Deanship of Scientific Research, Bahrain University. Author: Mattar E., 2010.

Tech-15: PROJECT REPORT: Co-Author of: Intelligent Mobile Robotics System: Intelligent Interaction Capabilities with an Active Stereo Vision-Path Planning Navigation in Unstructured Hazardous Environments ASTP-09, Submitted to National Plan for Science and Technology, King Saud University, KSA.

PUBLICATION LIST: (v): Local Publications: Samples of Articles for Local Engineering Magazines: Local Publications

Eng-01: Robotics Technology, Publication of Bahrain Society of Engineers, Al-Muhandis Magazine.

Eng-02: Robotics and Tomorrow Technology, AKH Engineering Press, 1997.

Eng-03: A Robotics Arm System Built at University of Bahrain, Engineering News in, AYAM Press, 1996.

Eng-04: Intelligent House of the Future, Engineering News in, AYAM Press, 20th of March 2000.

- Eng-05: Electrical Energy Conservation and Smart Houses, JDN Press, 21st March 2000.
- Eng-06: Face Value: ANN Based Face Recognition and Feature Control, UOB News and Views Magazine, 1999.
- Eng-07: Engineering of Robotics Arm Design, In UOB, News and Views Magazine, 1997.
- Eng-09: Engineering Education, AKH Engineering Press, 22nd of July 1998.
- Eng-10: Robot Technology and its Use in Bahrain, in the Al-Mohandis (Publication of BSE),1997.
- Eng-11: Engineering Education, Engineering News in, AYAM Press, 2000.
- Eng-12: Neural Network for Power Demand Predication in Bahrain, Engineering UOB News And Views, June 2000.
- Eng-13: Micro-Robot Technology, University of Bahrain, News and Views, October, 2000.
- Eng-14: Advanced Robot Applications, Al-Muhandis Magazine (Publication of BSE), December, 2000.
- Eng-15: Artificial Biology, UOB Engineering News and Views Magazine, November 2001.
- Eng-16: Humanoid Robots: Is it a fiction or a Reality, Engineering News, AKHEJ Press, 3rd January 2002.
- Eng-17: Intelligent Robotics Arm at UOB: New Dimensions Towards AI and Sciences For Engineering Education, UOB News and Views, March 2003.
- Eng-18: Scientific Research UOB, (News and Views Magazine), May 2004 Robotics Arm Control: Educational Example of Teaching Intelligence and Control, BSE, Magazine, February 2007.
- ${\it Eng-19} \colon {\rm GCC\ Electronics\ Industry,\ Publication\ of\ Bahrain\ Society\ of\ Engineers,\ BSE\ Magazine,\ June\ 2007.}$
- Eng-20: Scientific Research in GCC, in Engineering, WD Press, 26th July, 2010 Bahrain Educational Platform, in Engineering, WD Press, 11th October, 2010.

OTHER ENGAGEMENTS AND HOBBIES:

I do have other hobbies. This includes a number of sports, and in particular (football), and (long distance walking). In addition, I like reading about history.